

EFFECTS, ASYNCHRONY, AND CHOICE IN ARROWIZED FUNCTIONAL REACTIVE PROGRAMMING

Daniel Winograd-Cort

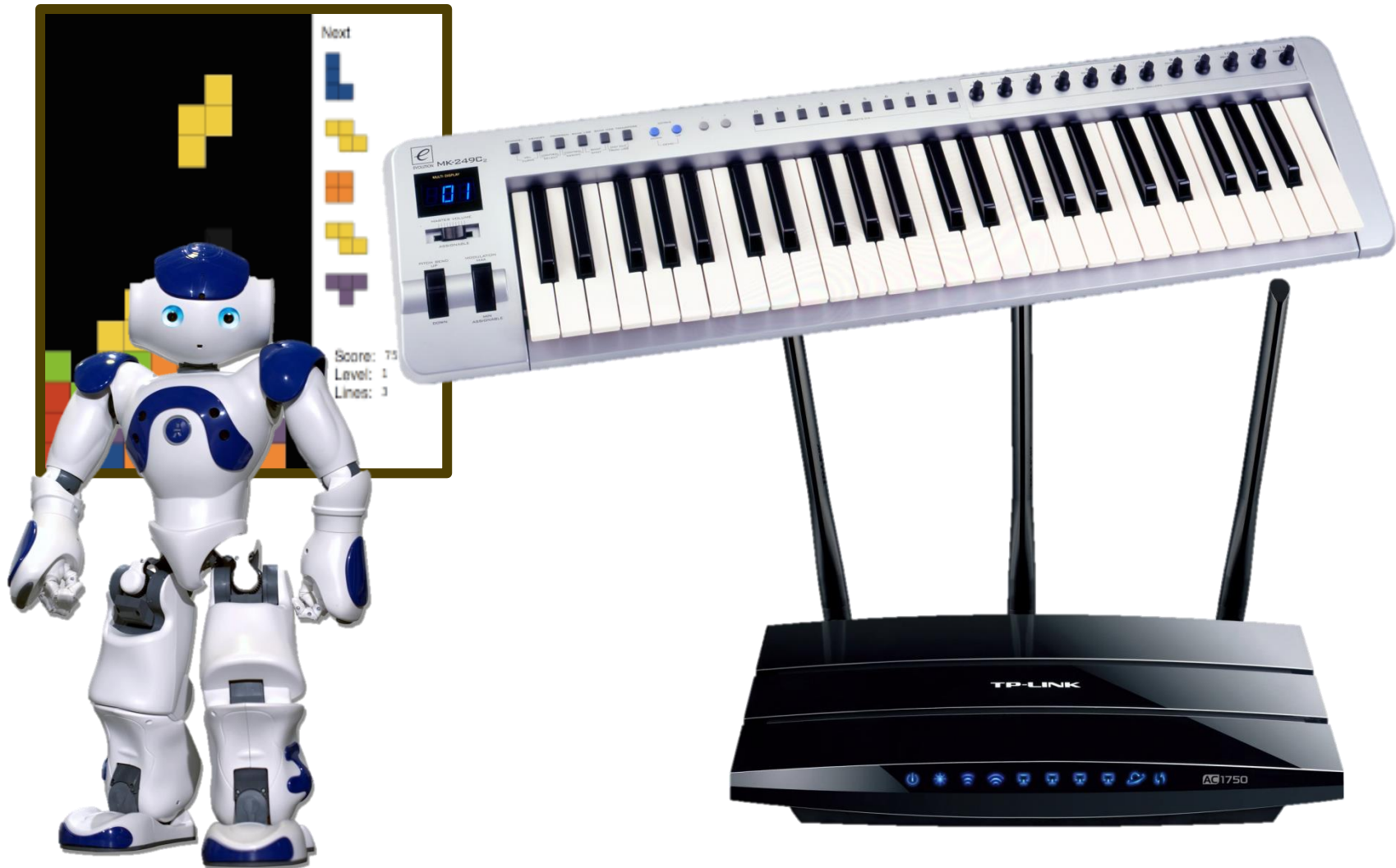
Department of Computer Science
Yale University
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Functional Reactive Programming

- Functional programming that can react to change.
 - ▣ Time is a built-in aspect of the design.
- One programs with *continuous values* and *streams of events*.
 - ▣ Values themselves are time-dependent.
 - ▣ The computation is time-independent.
- FRP is required to be ...
 - ▣ Causal by default.
 - ▣ Synchronous by default.
- Already in major use.

Functional Reactive Programming



GUI Example

- We would like a graphical user interface:
 - ▣ One textbox displays a temperature in Celsius.
 - ▣ Another displays the temperature in Fahrenheit.
- Updating one value should automatically update the other.

GUI Example

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 - ▣ One textbox displays a temperature in Celsius.
 - ▣ Another displays the temperature in Fahrenheit.
- Updating one value should automatically update the other.
- -Demo-
- We will explore this with and without FRP.

Java 7 with Swing

```
public class TemperatureConverter extends JFrame {
    JTextField celsiusField;
    JTextField fahrenheitField;

    public TemperatureConverter(String name) {
        super(name);
        initGUI();
        initListeners();
    }

    private void initGUI() {
        celsiusField = new JTextField(5);
        fahrenheitField = new JTextField(5);

        Container pane = this.getContentPane();
        pane.setLayout(new FlowLayout());
        pane.add(celsiusField);
        pane.add(new JLabel("Celsius"));
        pane.add(new JLabel("="));
        pane.add(fahrenheitField);
        pane.add(new JLabel("Fahrenheit"));
    }

    public static void main(String[] args) {
        javax.swing.SwingUtilities.invokeLater(new Runnable() {
            public void run() {
                TemperatureConverter frame =
                    new TemperatureConverter("Temperature Converter");
                frame.setDefaultCloseOperation(JFrame.EXIT_ON_CLOSE);
                frame.pack();
                frame.setVisible(true);
            }
        });
    }
}
```

* Code from <https://github.com/eugenkiss/7guis>

```
private void initListeners() {
    celsiusField.getDocument().addDocumentListener(
        new DocumentListener() {
            public void insertUpdate(DocumentEvent e) { update(); }
            public void removeUpdate(DocumentEvent e) { update(); }
            public void changedUpdate(DocumentEvent e) { update(); }

            private void update() {
                if (!celsiusField.isFocusOwner() ||
                    !isNumeric(celsiusField.getText())) return;
                double celsius =
                    Double.parseDouble(celsiusField.getText().trim());
                double fahrenheit = cToF(celsius);
                fahrenheitField.setText(
                    String.valueOf(Math.round(fahrenheit)));
            }
        });
    fahrenheitField.getDocument().addDocumentListener(
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            public void changedUpdate(DocumentEvent e) { update(); }

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                if (!fahrenheitField.isFocusOwner() ||
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                double fahrenheit =
                    Double.parseDouble(fahrenheitField.getText().trim());
                double celsius = fToF(fahrenheit);
                celsiusField.setText(
                    String.valueOf(Math.round(celsius)));
            }
        });
}
```

Java 8 with ReactFX (FRP)

```
public class TemperatureConverterReactFX extends Application {

    public void start(Stage stage) {
        TextField celsius = new TextField();
        TextField fahrenheit = new TextField();

        EventStream<String> celsiusStream =
            EventStreams.valuesOf(celsius.textProperty()).filter(Util::isNumeric);
        celsiusStream.map(Util::cToF).subscribe(fahrenheit::setText);
        EventStream<String> fahrenheitStream =
            EventStreams.valuesOf(fahrenheit.textProperty()).filter(Util::isNumeric);
        fahrenheitStream.map(Util::fToC).subscribe(celsius::setText);

        HBox root =
            new HBox(10, celsius, new Label("Celsius ="), fahrenheit, new Label("Fahrenheit"));
        root.setPadding(new Insets(10));

        stage.setScene(new Scene(root));
        stage.setTitle("Temperature Converter");
        stage.show();
    }

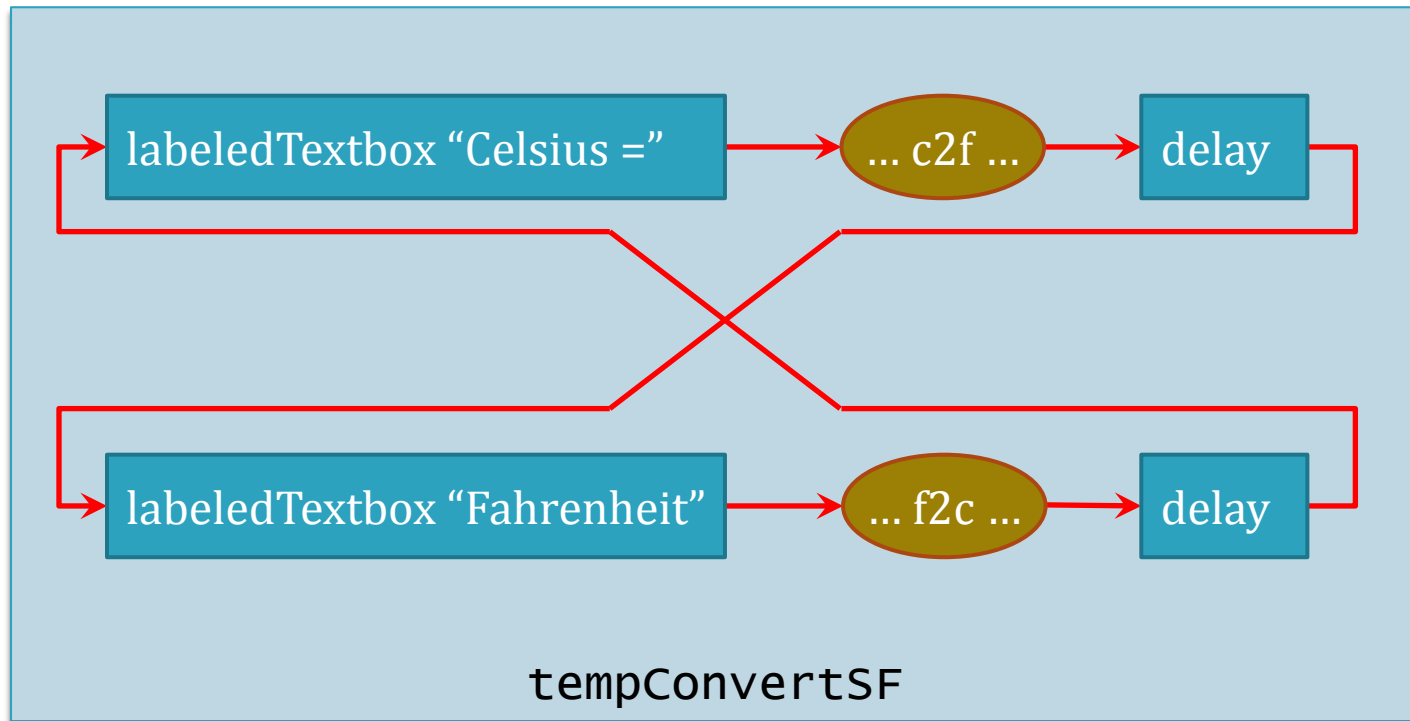
    public static void main(String[] args) {
        launch(args);
    }
}
```

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Arrows ...

- Are a well-founded concept inspired by category theory.
- Create a tighter semantic connection between data.
- Enforce the appropriate abstraction of time.
 - ▣ By removing direct access to streams, we eliminate certain memory leaks and non-causal behaviors.
- Have a static structure, which makes them ...
 - ▣ More suitable for resource constrained systems.
 - ▣ Highly amenable to optimizations (e.g. CCA).
- Have been used in Yampa, Nettle, Euterpea, etc.
- Look like *signal processing diagrams*.

AFRP (as a Diagram)



Haskell with UISF (AFRP)

```
tempConvertSF = leftRight $ proc () -> do
  rec c <- labeledTextbox "Celsius = " -< updateC
  f <- labeledTextbox "Fahrenheit" -< updateF
  updateF <- delay Nothing -< fmap (show . c2f) (c >>= readMaybe)
  updateC <- delay Nothing -< fmap (show . f2c) (f >>= readMaybe)
  returnA -< ()

main = runUI (defaultUIParams
              {uiSize=(400, 24), uiTitle="Temp Converter"})
  tempConvertSF
```

* <http://hackage.haskell.org/package/UISF>

Drawbacks of (Arrowized) FRP

- ❑ Data varies over time, but arrows cannot.
 - ▣ This lack of dynamic behavior limits expressivity.
- ❑ I/O Bottleneck
 - ▣ Pure FRP cannot perform effects.
 - ▣ All inputs and outputs must be routed manually.
 - ▣ This is a potential security leak.
- ❑ Synchrony can be restrictive.

My Contributions

- Extend arrows to allow “predictably dynamic” behavior [ICFP ‘14].
 - ▣ Non-interfering choice adds expressivity to arrows.
- Add concurrency and asynchrony [submitted ‘15].
 - ▣ Wormholes allow communication for concurrency.
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- Safe effects such as physical resource interaction memory access [PADL ‘12, HS ‘12].
 - ▣ Resource types address safety.

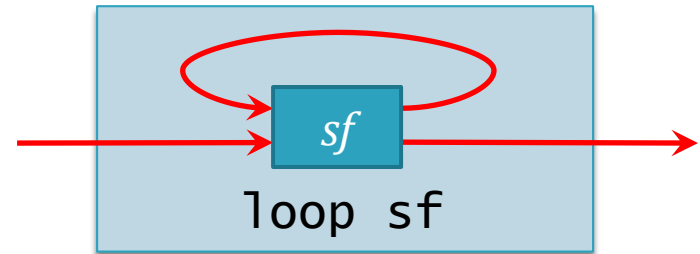
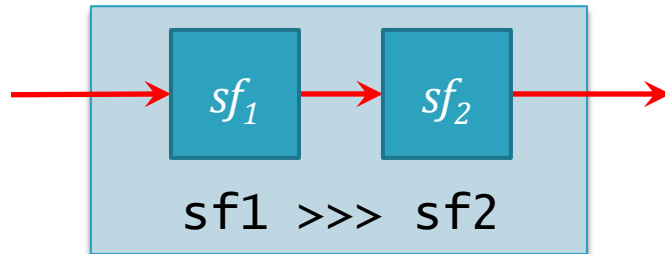
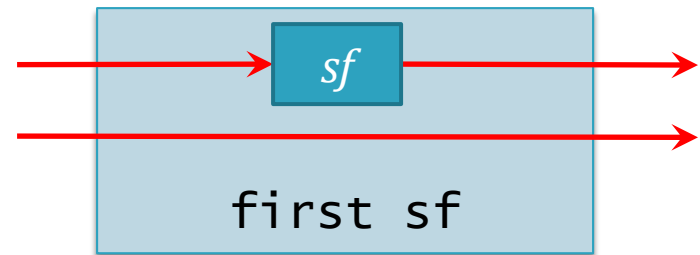
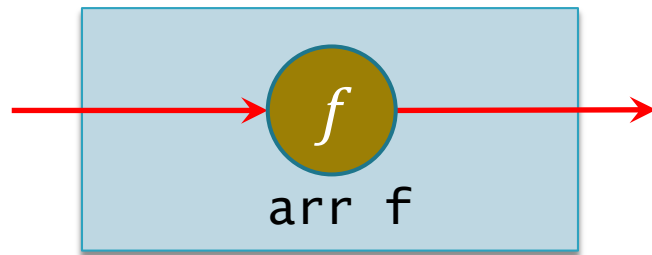
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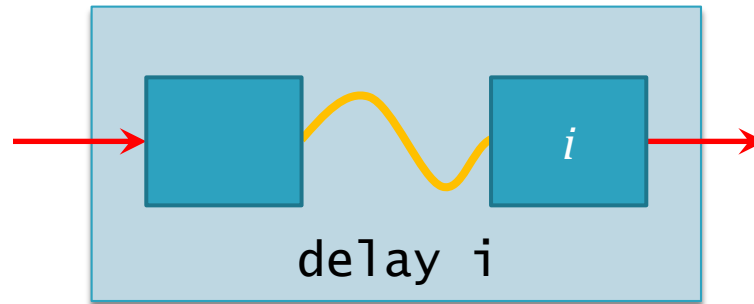
Expressing Arrows

How arrows work and what we need to express interesting computations

Standard Arrow Operators



Stateful Arrows



- With continuous semantics, the length of the delay approaches zero.
- When used in conjunction with loop, delay allows one to create stateful signal functions.

Dynamic Behavior



- Can we get more dynamic power for arrows?
- Why would we want that?



Example: Mind Map

Exploring predictably dynamic behavior

Example

- ❑ We would like a GUI to help a user build and navigate a “mind map.”
 - ▣ A mind map is a mapping from keywords to values.
 - ▣ A user can look up a key to see its values, and then add new values.
- ❑ The GUI’s appearance should dynamically update based on how many values the given key has.

Example

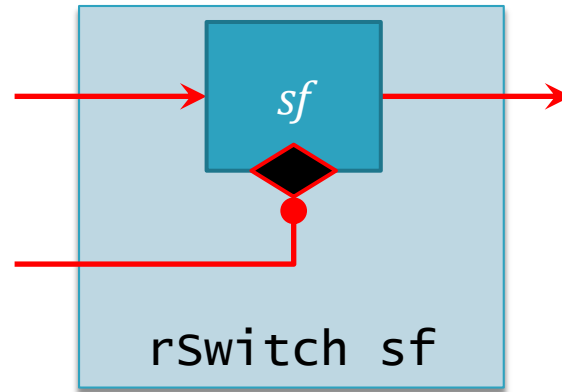
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- The GUI’s appearance should dynamically update based on how many values the given key has.
- -Demo-

Mindmap in code

```
mindmap :: MindMap -> UISF () ()
mindmap iMap = proc () -> do
  l <- textEntryField "Lookup" -< ()
  a <- textEntryField "Add" -< ()
  key <- accum "" -< fmap const l
  m <- accum iMap -< fmap (\v -> insertwith (++) key [v]) a
  title "key = " displayStr -< key
  runDynamic displayStr -< Map.findwithDefault [] key m
  returnA -< ()
```

□ How do we write runDynamic?

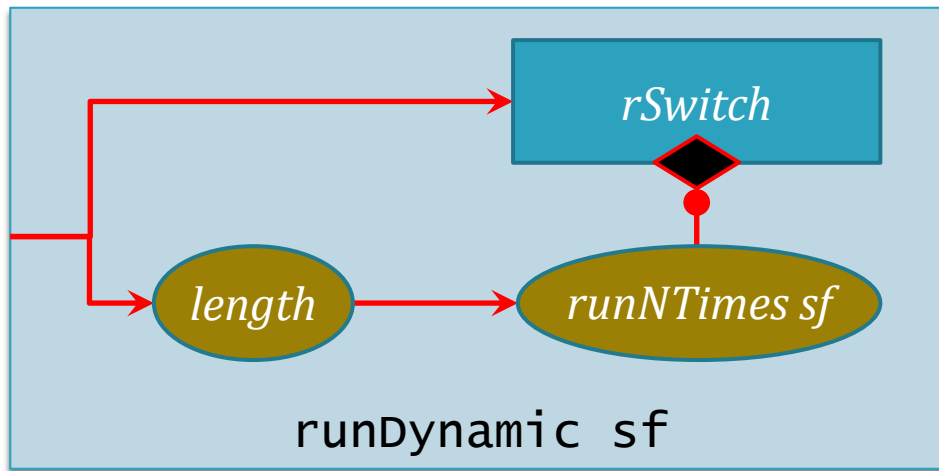
Higher Order Arrows



- The control signal determines the overall behavior.
 - ▣ This allows highly dynamic programs.
- Switched out signal functions are permanently off.
 - ▣ Switching can be used to increase performance.

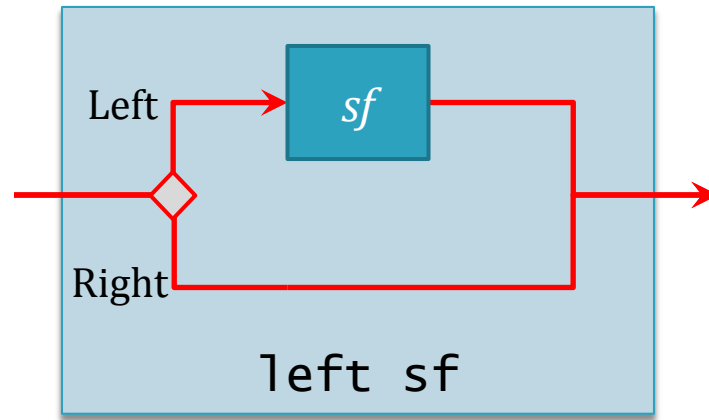
Implementing runDynamic

- We can create a new compound-widget when necessary and then switch into it:



- But this approach voids our static guarantees!
 - ▣ Arrows with switch are equivalent to Monads.
- It seems unnecessary – we are not running unknown functions.

Arrow Choice



- With choice, running the signal function is a dynamic decision.
- This seems to help, but it's not enough.
 - ▣ We get fixed branching, but not true recursion.

Arrow Choice Laws

Extension $\text{left } (\text{arr } f) = \text{arr } (\text{left } f)$

Functor $\text{left } (f \ggg g) = \text{left } f \ggg \text{left } g$

Exchange $\begin{aligned} \text{left } f \ggg \text{arr } (\text{right } g) &= \\ \text{arr } (\text{right } g) \ggg \text{left } f \end{aligned}$

Unit $f \ggg \text{arr Left} = \text{arr Left} \ggg \text{left } f$

Assoc $\begin{aligned} \text{left } (\text{left } f) \ggg \text{arr } \text{assoc}_+ &= \\ \text{arr } \text{assoc}_+ \ggg \text{left } f \end{aligned}$

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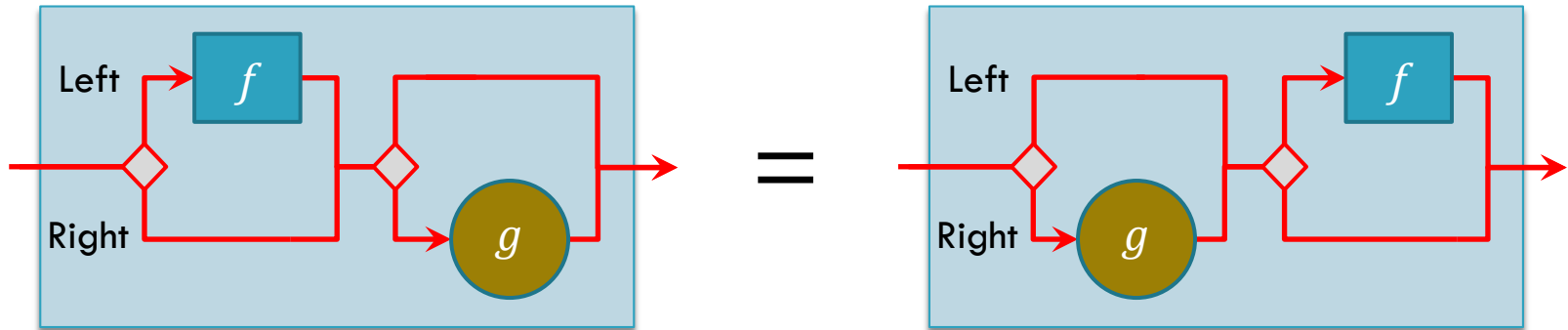
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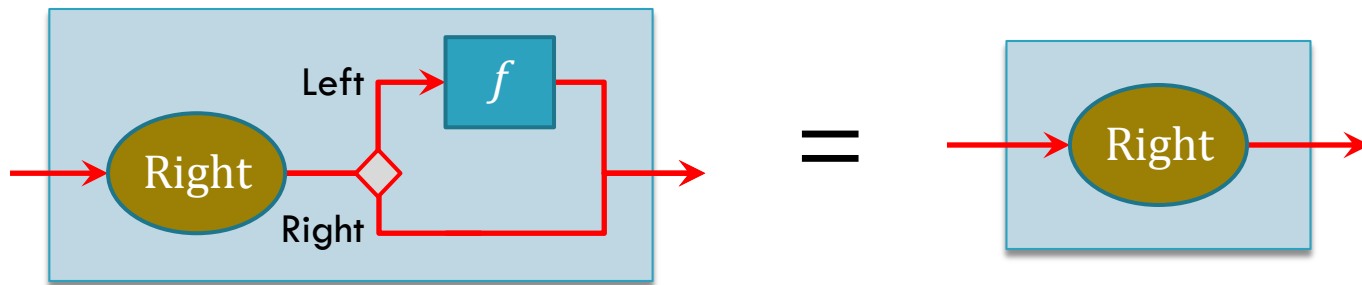
Exchange



- Why isn't this commutative?
 - ▣ Some arrows have effects.
 - ▣ For instance, UI SF uses arrow order to determine widget layout.
- These effects make recursion impossible.
- In general, arrows are not commutative, but for choice in FRP, they can be.

Non-Interference

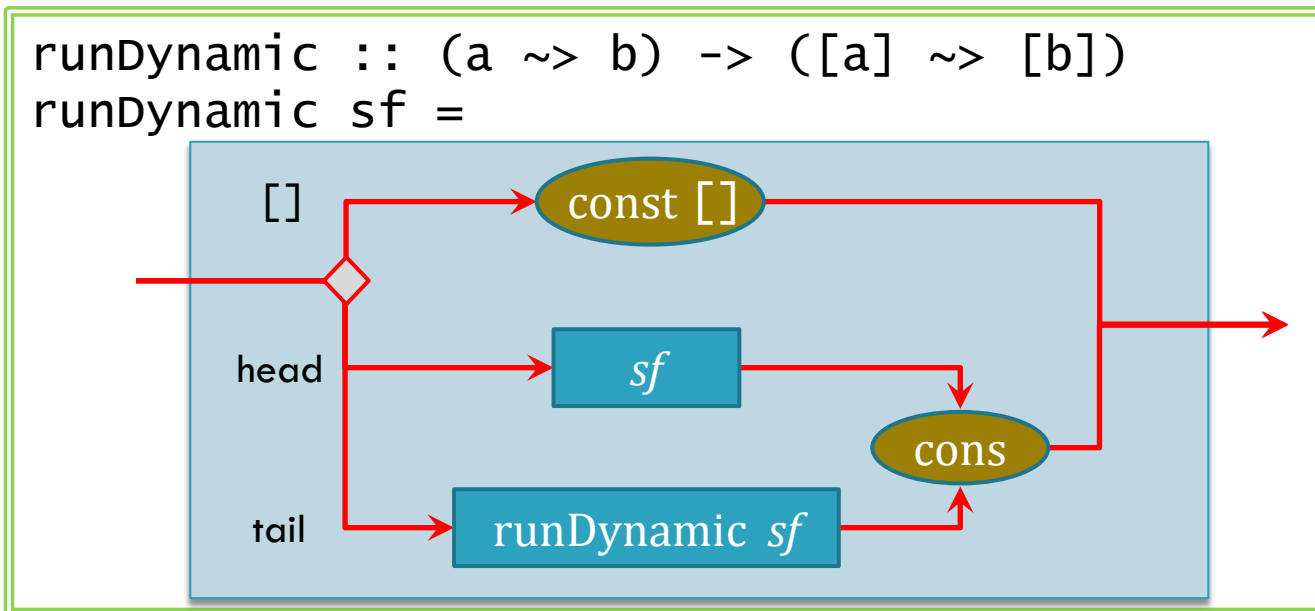
- We strengthen exchange into **non-interference**



- If the input value is Right, then the program will behave the same whether there is a left function after it or not.
- The unused branch is now guaranteed to not run.
- Now we can use Arrow Choice for recursion!

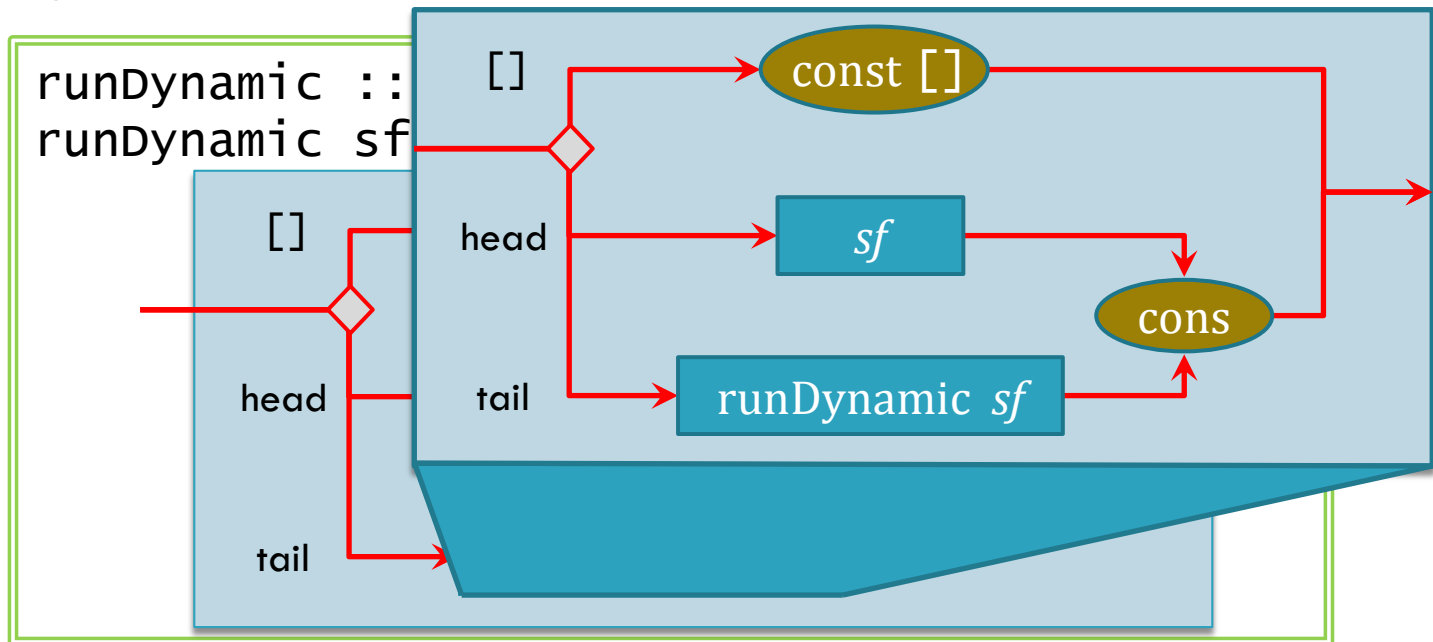
runDynamic Revisited

- Arrowized recursion allows us to write this without using switch.



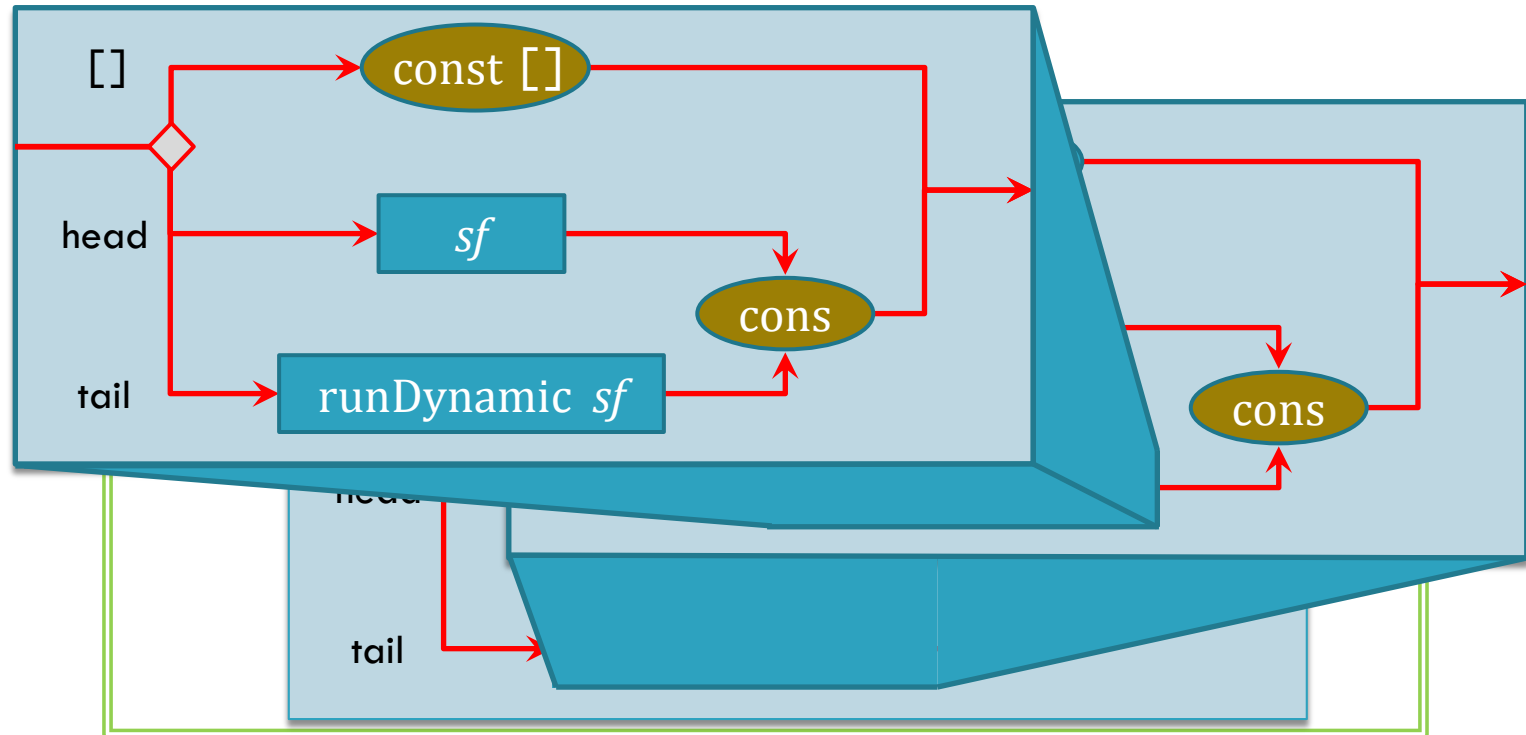
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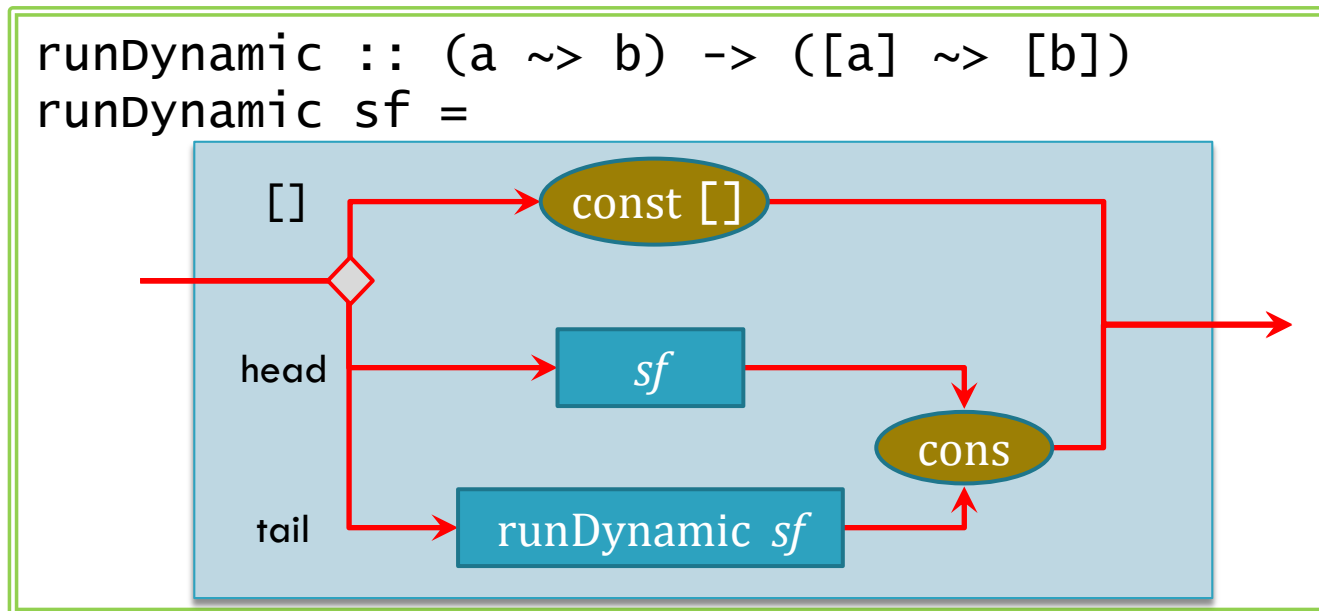
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runDynamic Revisited

- Arrowized recursion allows us to write this without using switch.



- The arrow structure is not technically static, but it is predictably dynamic.

Non-Interfering Choice Wrap-Up

- Like switch, non-interfering choice (and thus arrowized recursion) only computes when needed.
- The predictable nature of non-interfering choice does not interfere with optimizations.
 - ▣ The CCA transformation is still applicable.
- Time complexity can now be variable, but resource allocation is still static (arrow dependent).

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Example: Connect Four

Allowing local asynchronous concurrency

Example



- We would like a GUI to play a game of Connect 4.
 - ▣ It should follow the rules of the game.
 - ▣ After the user makes a play, an AI should play.

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- -Demo-

Connect Four GUI

```
connectFour = proc () -> do
  rec aiLevel <- title "AI Level" (hislider 1 (0, 5) 2) -< ()
  select <- displayBoard numCols 10 -< board
  board <- hold initBoard -< fmap (makeMove board) $
    case (turn board) of
      X -> fmap (,X) select
      O -> findBestMove 0 aiLevel board
  case (isWin board) of
    Nothing -> label "" -< ()
    Just X -> label "You win!" -< ()
    Just O -> label "You lose!" -< ()
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```

- When we ramp up the AI level, we find a problem.
- ▣ -Demo-

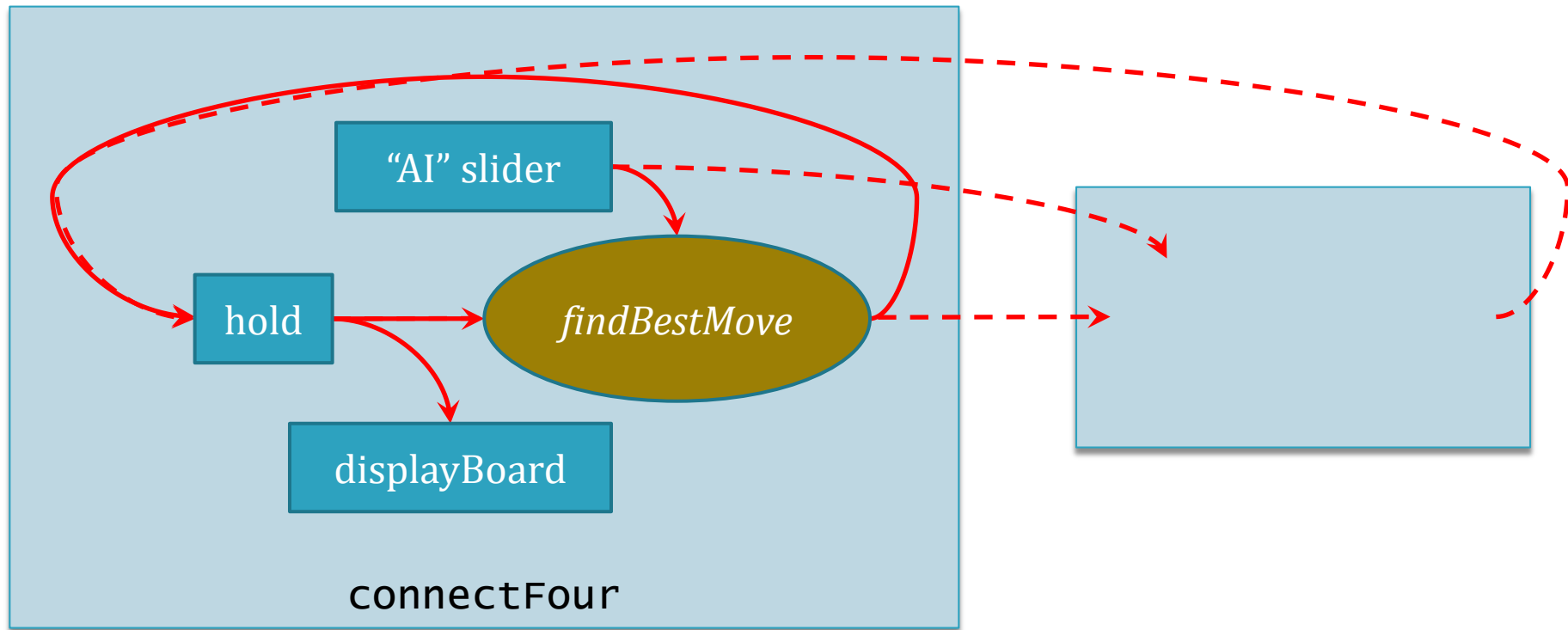
Synchrony Can Be a Burden

- The two parts would like to run at different rates.
 - ▣ The GUI should continue running at $\sim 60\text{FPS}$.
 - ▣ The AI should be allowed to run as slow as it needs to.
- The synchronous assumption of FRP is too strong.
- Other examples include ...
 - ▣ Memory reads together with hard drive seeks.
 - ▣ Packet routing together with network map updating.
 - ▣ Sound synthesis together with a GUI interface.

Asynchrony

- Let us allow **multiple processes**, each with its own notion of **time**.
 - ▣ Each will individually remain synchronous and causal.
 - ▣ However, they will no longer synchronize.

Connect Four GUI Diagram

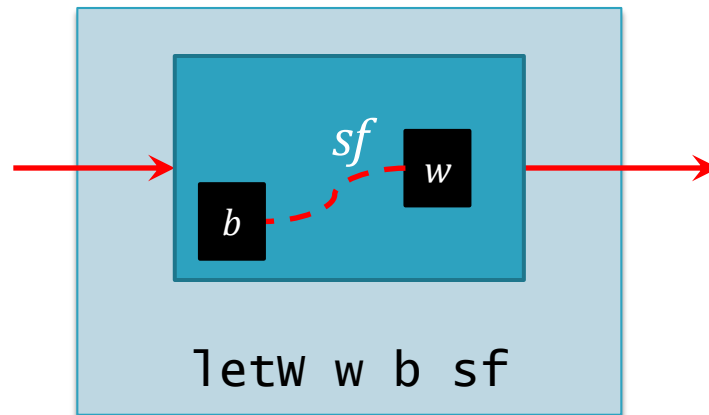
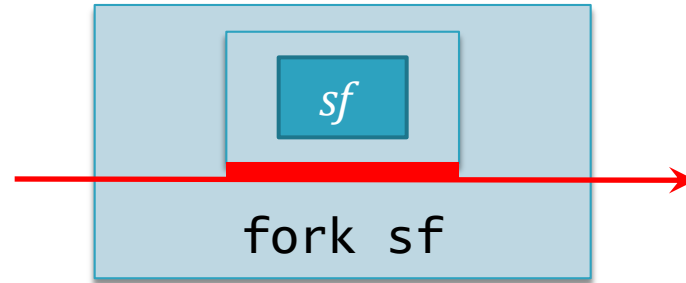


□ But what are those dashed lines?

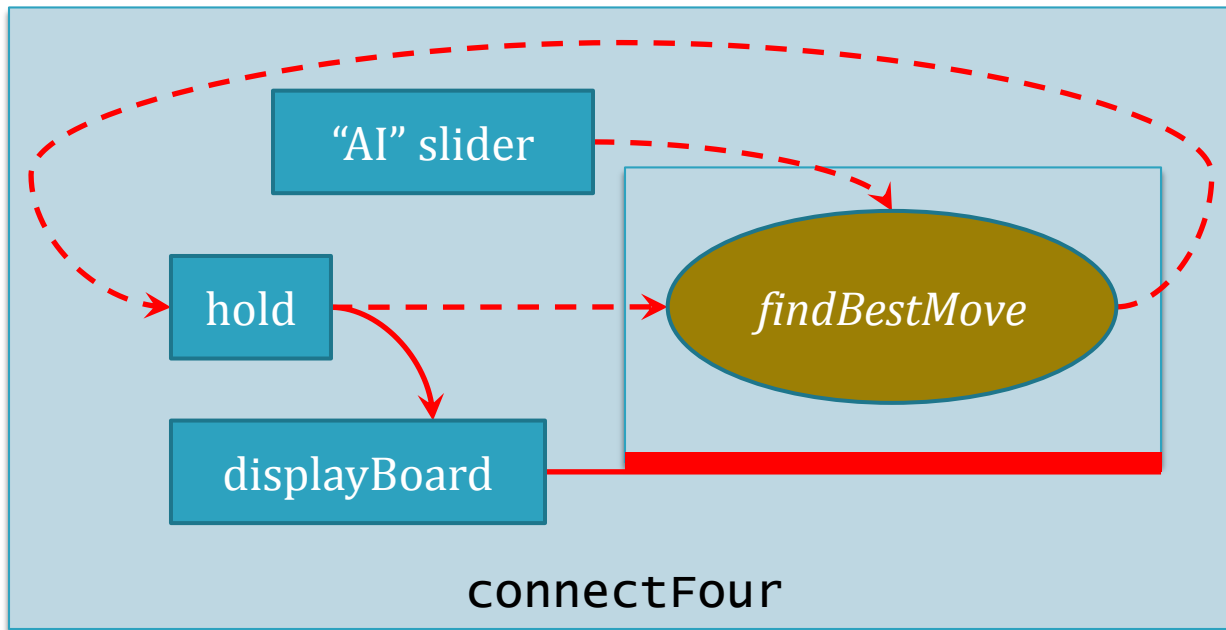
Inter-Process Communication

- We need a way to communicate data from one time stream to another.
- Data needs to get **time dilated** – either **stretched or compressed**.
- A special form of channel: **Wormholes**
 - ▣ Wormholes have a **blackhole** for writing to and a **whitehole** for reading from.
 - ▣ Wormholes automatically dilate their data.

New Operators



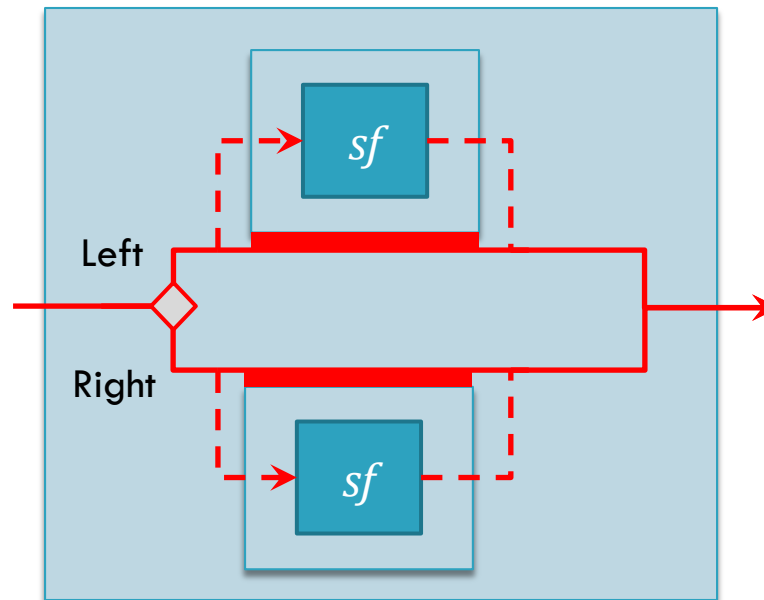
Connect Four GUI Diagram 2



- Now, *findBestMove* can run with its own clock.
- The data is communicated clearly via wormholes.

Maintaining Modular Consistency

- How can we control forked processes?



Asynchronous Choice

- Remember that **data is time-dependent**.
 - ▣ When a signal function has no incoming data, it must **freeze**.
 - ▣ Likewise, if a fork has no incoming data, it **freezes its forked process**.
- We achieve this while guaranteeing consistency.
 - ▣ Treat every moment in time as a transaction.
 - ▣ Freezing may occur between transactions.

Asynchrony Wrap-Up

- We can create **multiple time streams** for different FRP components.
 - ▣ Each time stream is **internally synchronous and deterministic**.
- We can communicate between time streams in a clear way with **wormholes**.
 - ▣ Data is automatically **time dilated**.
- We can govern time streams using **non-interfering choice**.

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Example: MIDI Echo Player

Allowing effects in a meaningful yet safe manner

Example

- We would like a GUI to control the parameters of an echo effect that we can add to a MIDI stream.
 - ▣ MIDI stands for Musical Instrument Digital Interface.
 - ▣ An echo decays and loops the sound.
- The program should read from and write to a MIDI port.

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- The program should read from and write to a MIDI port.
- -Demo-

Echo GUI

```
echo :: UISF () ()
echo = proc () -> do
  m <- midiIn -< ()
  r <- title "Decay rate"      (hslider (0, 0.9) 0.6) -< ()
  f <- title "Echoing frequency" (hslider (1, 10) 3) -< ()
  rec let m' = m <> s
        s <- vdelay -< (1.0 / f, decay 0.1 r m')
  midiOut -< m'
```

- Let's also add a metronome tick to this.

Echo GUI

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```

```
metronomeTick :: UISF () ()
metronomeTick = proc () -> do
  bpm <- title "Metronome BPM" (hslider (40, 200) 100) -< ()
  e <- timer -< 60 / bpm
  midiOut -< makeTick e
```

Echo GUI

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echo :: UISF () ()
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```

```
runUI defaultUIParams (echo >>> metronomeTick)
```


Multiple midiOut Effects

- What happens when we send MIDI output twice in one program?
 - ▣ The two input streams merge in some way?
 - ▣ The top input stream processes first?
- This may break our functional guarantee.
 - ▣ Blocks of code are no longer modular.
 - ▣ The UISF layout is determined by program structure.
 - Layout is determined statically (“predictably dynamic”).
 - Computation and layout are totally separate.

Adding Effects

- To make effects safe, we must limit how we use effectful signal functions.
 - ▣ If an effect is used, it **can only be used in one place**.
- We achieve this by tagging signal functions at the type level with **resource types** and restricting their composition.

Resource Typed Arrow Operators

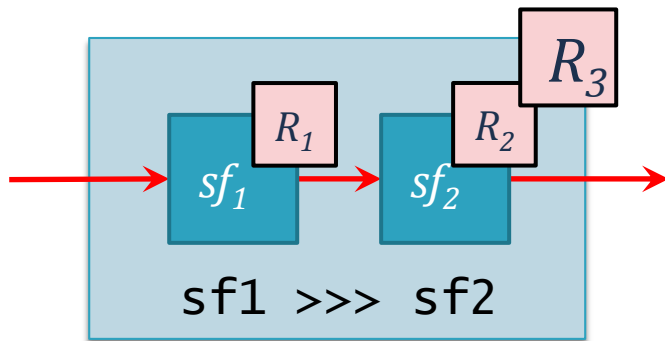
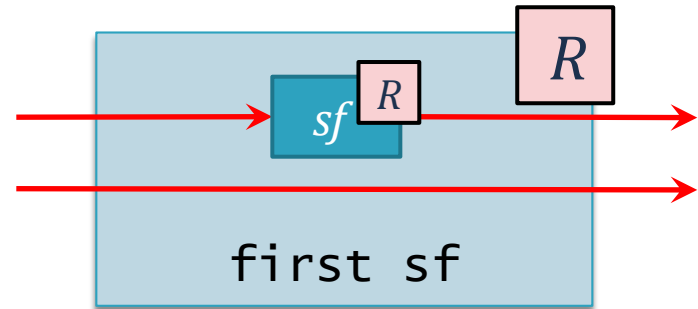
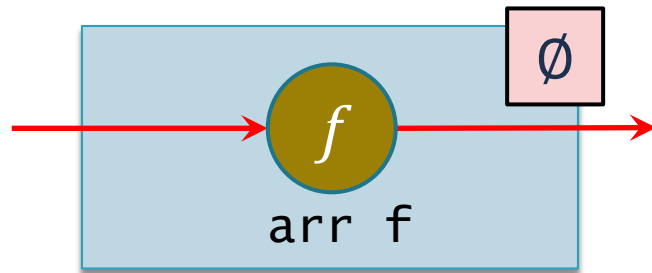
$$\text{Ty-Arr} \quad \frac{\Gamma \vdash e : \alpha \rightarrow \beta}{\Gamma; \Psi \vdash \text{arr } e : \alpha \overset{\emptyset}{\rightsquigarrow} \beta}$$

$$\text{Ty-First} \quad \frac{\Gamma; \Psi \vdash e : \alpha \overset{R}{\rightsquigarrow} \beta}{\Gamma; \Psi \vdash \text{first } e : (\alpha \times \gamma) \overset{R}{\rightsquigarrow} (\beta \times \gamma)}$$

$$\text{Ty-Comp} \quad \frac{\begin{array}{c} \Gamma; \Psi \vdash e_1 : \alpha \overset{R_1}{\rightsquigarrow} \beta \quad \Gamma; \Psi \vdash e_2 : \beta \overset{R_2}{\rightsquigarrow} \gamma \\ R_1 \uplus R_2 = R \end{array}}{\Gamma; \Psi \vdash e_1 >>> e_2 : \alpha \overset{R}{\rightsquigarrow} \gamma}$$

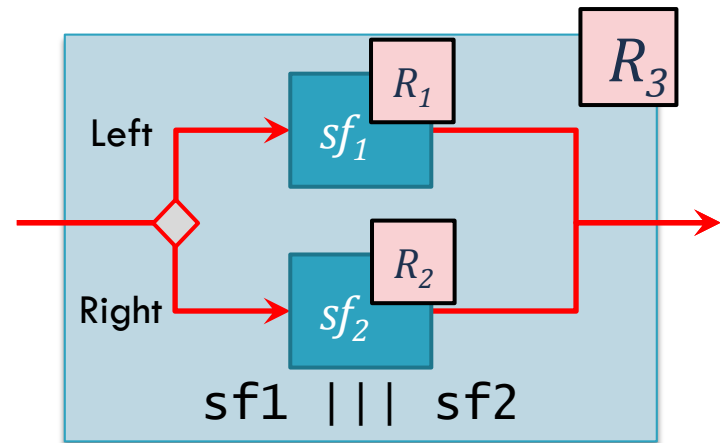
$$\text{Ty-Chc} \quad \frac{\begin{array}{c} \Gamma; \Psi \vdash e_1 : \alpha \overset{R_1}{\rightsquigarrow} \gamma \quad \Gamma; \Psi \vdash e_2 : \beta \overset{R_2}{\rightsquigarrow} \gamma \\ R_1 \cup R_2 = R \end{array}}{\Gamma; \Psi \vdash e_1 ||| e_2 : (\alpha + \beta) \overset{R}{\rightsquigarrow} \gamma}$$

Resource Typed Arrow Operators



$$R_1 \cup R_2 = R_3$$

$$R_1 \cap R_2 = \emptyset$$



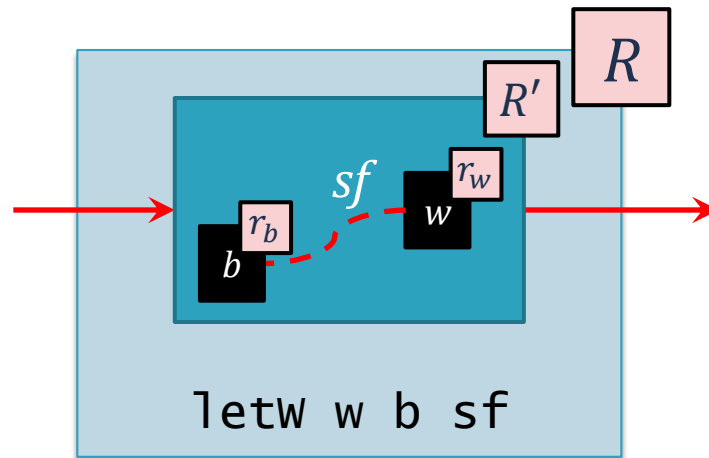
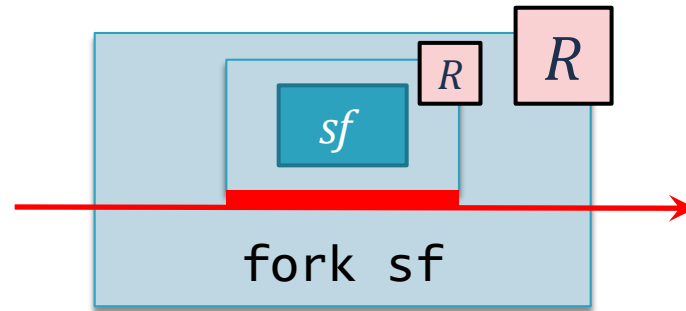
$$R_1 \cup R_2 = R_3$$

Resource Typed Arrow Operators

$$\text{Ty-Fork} \quad \frac{\Gamma; \Psi \vdash e : () \overset{R}{\rightsquigarrow} ()}{\Gamma; \Psi \vdash \text{fork } e : \alpha \overset{R}{\rightsquigarrow} \alpha}$$

$$\text{Ty-LetW} \quad \frac{\begin{array}{c} \Gamma; \Psi, r_w : \langle (), \text{List } \tau \rangle, r_b : \langle \tau, () \rangle \vdash e : \alpha \overset{R'}{\rightsquigarrow} \beta \\ \Gamma; \Psi \vdash e_i : \text{List } \tau \quad R = R' \setminus \{r_w, r_b\} \end{array}}{\Gamma; \Psi \vdash \text{letW } r_w \ r_b \ e_i \text{ in } e : \alpha \overset{R}{\rightsquigarrow} \beta}$$

Resource Typed Arrow Operators



$$R = R' \setminus \{r_b, r_w\}$$

Resource Signal Function

$$\text{Ty-RSF} \quad \frac{(r:\langle\tau_{in},\tau_{out}\rangle)\in\Psi}{\Gamma;\Psi\vdash rsf \ r : \tau_{in}^{\{r\}} \rightsquigarrow \tau_{out}}$$

- All physical devices have an associated virtual resource.

Resource Signal Function



- All physical devices have an associated virtual resource.

FRP I/O Effects

- Back to our example:
 - ▣ We can send MIDI data by using the MidiOut resource:



- We are assured that the input stream is **unique**.
- The **type** of a program shows its resource usage:
 - ▣ Our poorly-defined metronome/echo program will no longer type check.

```
echo          :: UISF {MidiIn, MidiOut} () ()
metronomeTick :: UISF {MidiOut}          () ()
echo >>> metronomeTick :: TYPE ERROR
```

Formalism

- Operational semantics describe the behavior of fork and wormholes with arrows.
- The semantics proceed in a 3-phase set of transitions:

| | |
|---|-----------------------|
| $e \mapsto e'$ | Evaluation transition |
| $(S, T, \mathcal{R}, \mathcal{W}) \Rightarrow (S', T', \mathcal{R}', \mathcal{W}')$ | Functional transition |
| $(T, \mathcal{R}, \mathcal{W}) \Downarrow (T', \mathcal{R}', \mathcal{W}')$ | Executive transition |

- The evaluation transition is a classic, non-strict, functional semantics.

Formalism – Functional Transition

$$\text{FT-FORK} \frac{p \text{ fresh}, \quad T' = T[p \mapsto \varepsilon \triangleright (e, (), \emptyset)]}{(K \triangleright (\text{fork } e, x, U), T) \Rightarrow (K \triangleleft (\text{fork } e \ p, x, U), T')}$$

$$\text{FT-FORK}_p \frac{T' = \mathbf{if} \ p \in \text{Dom}(T) \ \mathbf{then} \ T \ \mathbf{else} \ T[p \mapsto \varepsilon \triangleright (e, (), \emptyset)]}{(K \triangleright (\text{fork } e \ p, x, U), T) \Rightarrow (K \triangleleft (\text{fork } e \ p, x, U), T')}$$

$$\text{FT-RSF}_r \frac{r \in \mathcal{R} \quad U' = (r, x) :: U \quad y = \text{read } r \ \mathcal{R}(r)}{(K \triangleright (\text{rsf } r, x, U), \mathcal{R}, \mathcal{W}) \Rightarrow (K \triangleleft (\text{rsf } r, y, U'), \mathcal{R}, \mathcal{W})}$$

$$\text{FT-RSF}_w \frac{r \in \mathcal{W} \quad U' = (r, x) :: U \quad y = \text{read } r \ \mathcal{R}(\text{fst } \mathcal{W}(r))}{(K \triangleright (\text{rsf } r, x, U), \mathcal{R}, \mathcal{W}) \Rightarrow (K \triangleleft (\text{rsf } r, y, U'), \mathcal{R}, \mathcal{W})}$$

$$\text{FT-LETW} \frac{r \text{ fresh} \quad \mathcal{R}' = \mathcal{R}[r \mapsto (\varepsilon, e_i)] \quad \mathcal{W}' = \mathcal{W}[r_b \mapsto (r, B), r_w \mapsto (r, W)]}{(K \triangleright (\mathbf{letW} \ r_w \ r_b \ e_i \ \mathbf{in} \ e, x, U), \mathcal{R}, \mathcal{W}) \Rightarrow (K \triangleright (e, x, U), \mathcal{R}', \mathcal{W}')}$$

$$\text{FT-TIME} \frac{\begin{array}{l} \mathcal{R}_1 = \mathcal{R} \left[r \mapsto \text{update } r \ \mathcal{R}(r) \ x \mid (r, x) \in U, r \in \mathcal{R} \right] \\ \mathcal{R}_2 = \mathcal{R}_1 \left[r \mapsto \text{update } r_b \ \mathcal{R}_1(r) \ x \mid (r_b, x) \in U, \mathcal{W}(r_b) = (r, B) \right] \\ \mathcal{R}_3 = \mathcal{R}_2 \left[r \mapsto \text{update } r_w \ \mathcal{R}_2(r) \ x \mid (r_w, x) \in U, \mathcal{W}(r_w) = (r, W) \right] \end{array}}{(\varepsilon \triangleleft (e, (), U), \mathcal{R}, \mathcal{W}) \Rightarrow (\varepsilon \triangleright (e, (), \emptyset), \mathcal{R}_3, \mathcal{W})}$$

Formalism – Functional Transition

- Choice is specially designed to handle freezing:

$$\text{FT-CHC}_e \frac{x \mapsto x'}{(K \triangleright (e_1 \parallel e_2, x, U), T) \Rightarrow (K \triangleright (e_1 \parallel e_2, x', U), T)}$$

$$\text{FT-CHC}_{l1} \frac{T' = T \setminus (\text{getChildrenOf } T \ e_2)}{(K \triangleright (e_1 \parallel e_2, \text{Left } x, U), T) \Rightarrow (K; (\cdot \parallel e_2) \triangleright (e_1, x, U), T')}$$

$$\text{FT-CHC}_{l2} \frac{}{(K; (\cdot \parallel e_2) \triangleleft (e_1, z, U), T) \Rightarrow (K \triangleleft (e_1 \parallel e_2, z, U), T)}$$

$$\text{FT-CHC}_{r1} \frac{T' = T \setminus (\text{getChildrenOf } T \ e_1)}{(K \triangleright (e_1 \parallel e_2, \text{Right } y, U), T) \Rightarrow (K; (e_1 \parallel \cdot) \triangleright (e_2, y, U), T')}$$

$$\text{FT-CHC}_{r2} \frac{}{(K; (e_1 \parallel \cdot) \triangleleft (e_2, z, U), T) \Rightarrow (K \triangleleft (e_1 \parallel e_2, z, U), T)}$$

Formalism – Executive Transition

- The executive transition runs the program.

$$\text{EXEC} \quad \frac{(p, S) \in T \quad (S, T \setminus \{(p, S)\}, \mathcal{R}, \mathcal{W}) \Rightarrow (S', T', \mathcal{R}', \mathcal{W}')}{(T, \mathcal{R}, \mathcal{W}) \Downarrow (T' \cup \{(p, S')\}, \mathcal{R}', \mathcal{W}')}$$

- It chooses a process p non-deterministically and fairly and runs it.

Program execution is the application of the reflexive transitive closure over the EXEC transition \Downarrow starting with initial parameters $T = \{(p, \varepsilon \triangleright (e, (), \varepsilon))\}$, $\mathcal{R} = \mathcal{R}_0$, and $\mathcal{W} = \emptyset$ where p is a fresh process ID, e is a process, and \mathcal{R}_0 is an initial mapping of resources representing those of the real world.

Theorem: Safety

For a program $P: \rightarrow \boxed{sf} \xrightarrow{R} \rightarrow$, we know:

- No program states will ever interact with a resource $r \notin R$.
- No two processes in P can interact with the same resource.
- No moment of time in P will ever interact with a resource more than once.

- ▣ The type reveals **which resources a program can interact with** when run.
- ▣ Forked **processes** will **respect** each others' resources.
- ▣ All resource streams are **guaranteed unique**.

Theorem: Resource Commutativity

For any S and r , if $(S, \mathcal{R}, \mathcal{W}) \hookrightarrow_p (S', \mathcal{R}', \mathcal{W}')$ is the set of states $S_0 \dots S_n$ and there exists $i < n$ such that $S_i = (K \triangleright (rsf\ r, _, U_i))$ and $S_{i+1} = (K \triangleleft (rsf\ r, x, U_{i+1}))$, then x will be the same for all S regardless of i .

- ▣ Resource types **enforce** data commutativity.
- ▣ Programs stay functional and modular.
- ▣ Reasoning about behavior through diagrams remains clear.

Effects Wrap-Up

- **Effects** can be inserted directly into FRP programs.
 - ▣ **Resource types** assure **safety** and data **commutativity**.
 - ▣ Invalid effect interactions are eliminated **statically**.
- Formal semantics demonstrate features.
 - ▣ Proofs are in the dissertation.



Other FRP Enhancing Efforts

More uses for Wormholes

- Wormholes provide communication **between** processes, but what if both ends are in the **same** process?
 - ▣ What kind of time dilation occurs?

More uses for Wormholes

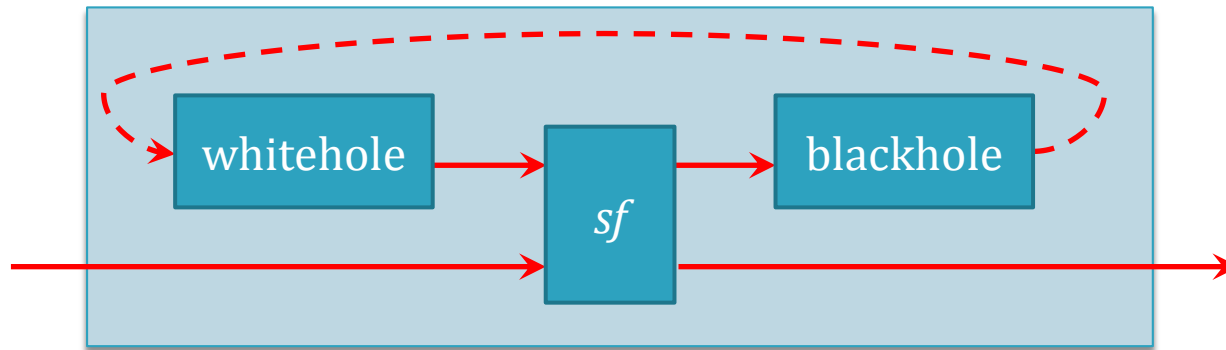
- Wormholes provide communication **between** processes, but what if both ends are in the **same** process?
 - ▣ What kind of time dilation occurs?
- A blackhole into a whitehole:



- We create delay.

More uses for Wormholes

- Wormholes provide communication **between** processes, but what if both ends are in the **same** process?
- ▣ What kind of time dilation occurs?
- A whitehole into a blackhole:



- We create a strictly causal form of loop.

More uses for Wormholes

- Wormholes provide communication **between** processes, but what if both ends are in the **same** process?
 - ▣ What kind of time dilation occurs?
- In arbitrary locations:
 - ▣ We achieve non-local memory mutation.

Other Results

- **Settability** – A transformation applicable to AFRP that creates access to internal state.
 - <https://github.com/dwincort/SettableArrow>
- **A non-interfering choice extension to CCA with comparable performance.**
 - <https://github.com/dwincort/CCA>
- **An alternate back-end for rec-delay syntax that uses wormholes to statically prevent infinite loops.**



Conclusions

Contributions

- ❑ Safer FRP
 - ▣ Resource types track and limit effects.
- ❑ More Efficient FRP
 - ▣ Static arrows can be greatly optimized.
 - ▣ Concurrent processing can leverage multiple cores.
- ❑ More Expressive FRP
 - ▣ Non-interfering choice provides predictably dynamic behavior.
 - ▣ Effects can be used within the computation.
 - ▣ Concurrency allows multiple simultaneous clock rates.

Future Work

- ❑ Dynamic Resource Types
 - ▣ Wormhole resources cannot be fully implemented in GHC without a significant extension.
- ❑ Deterministic Parallelism
 - ▣ Can we make deterministic guarantees about predictable concurrent programs?
- ❑ Optimization
 - ▣ CCA transformation with Non-Interfering Choice needs to be more robust.

Thank you!



Questions?

Contributions

- ❑ Safer FRP
 - ▣ Resource types track and limit effects.
- ❑ More Efficient FRP
 - ▣ Static arrows can be greatly optimized.
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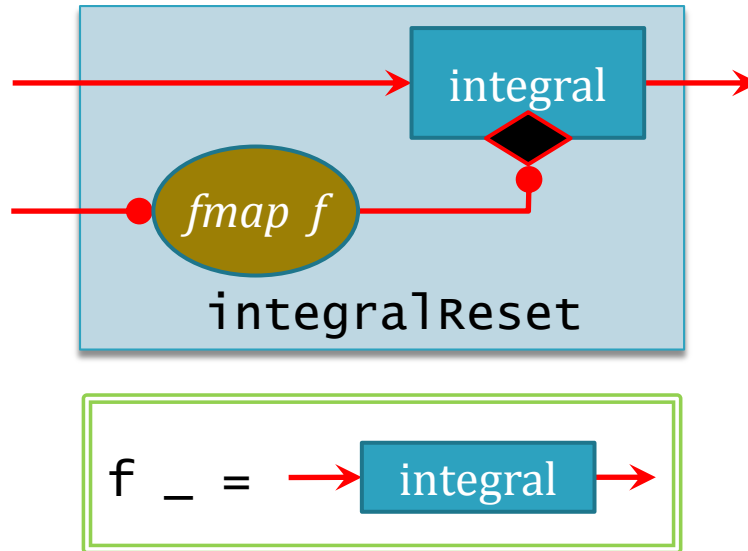
EXTRA SLIDES

Settability

Saving, loading, and resetting signal functions

Example: IntegralReset

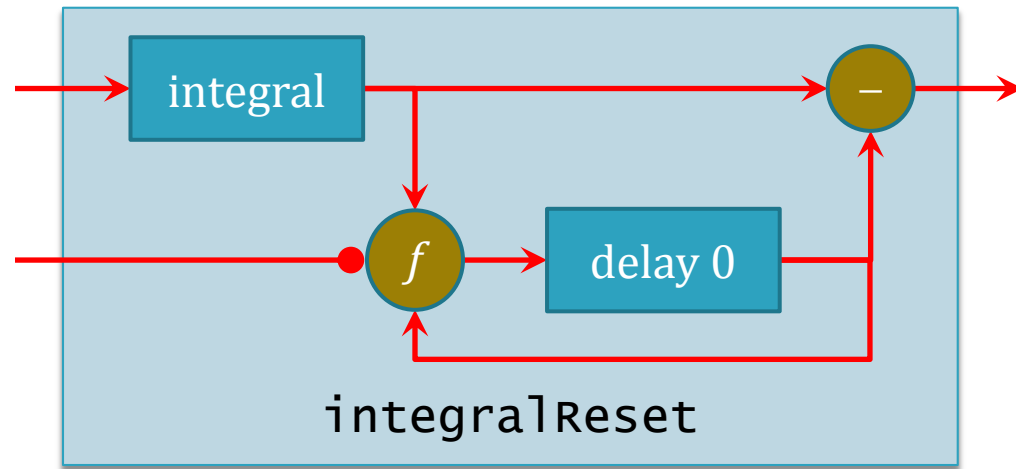
- A signal function that calculates an integral but can be reset with an event.



- Can we even do this without switch?

Example: IntegralReset

- Without switch, we can simulate a reset, but we can't modify integral itself.



$f \ v \ e \ k = \text{if isEvent } e \text{ then } v \text{ else } k$

- This solution is inelegant and does not scale.

Resetting State

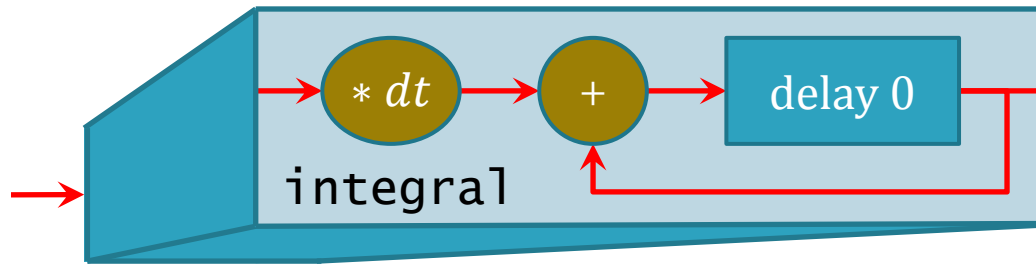
- We want to access the state inside a signal function.



- But what's inside of an arbitrary signal function?
- All state is saved with loop and delay.

Resetting State

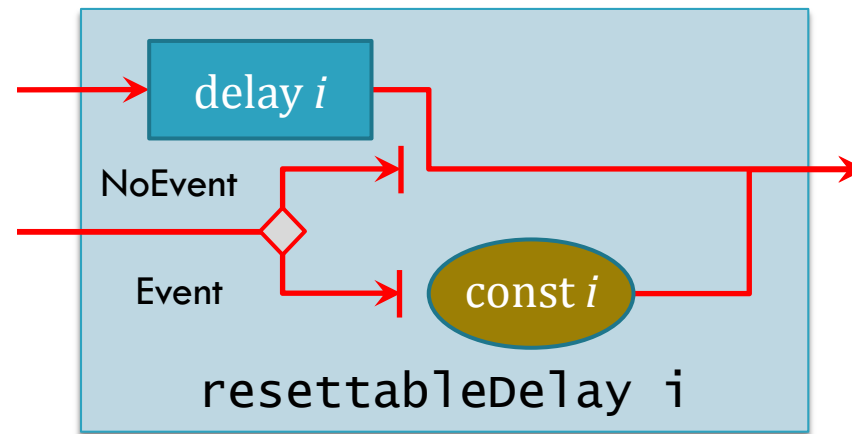
- We want to access the state inside a signal function.



- If we could reach in and restart the delay, then integral would behave as if it just started.

Resettable Delay

- Let's consider a new delay that can be reset directly.



- When the event is given, `resettableDelay` reverts to its starting state.
- Does this scale? **YES**

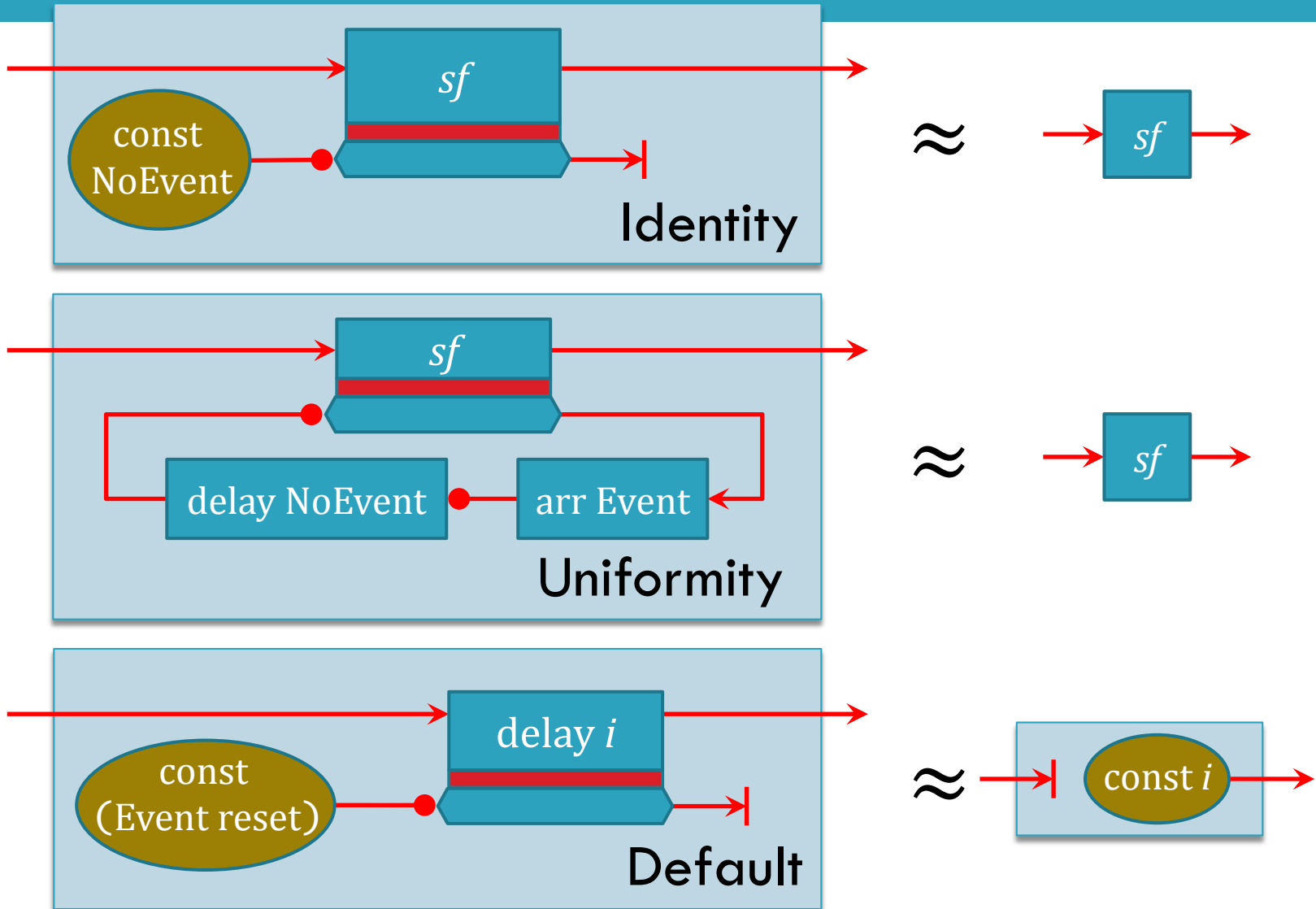
General Settability

- We can take any signal function and transform it into a settable signal function:



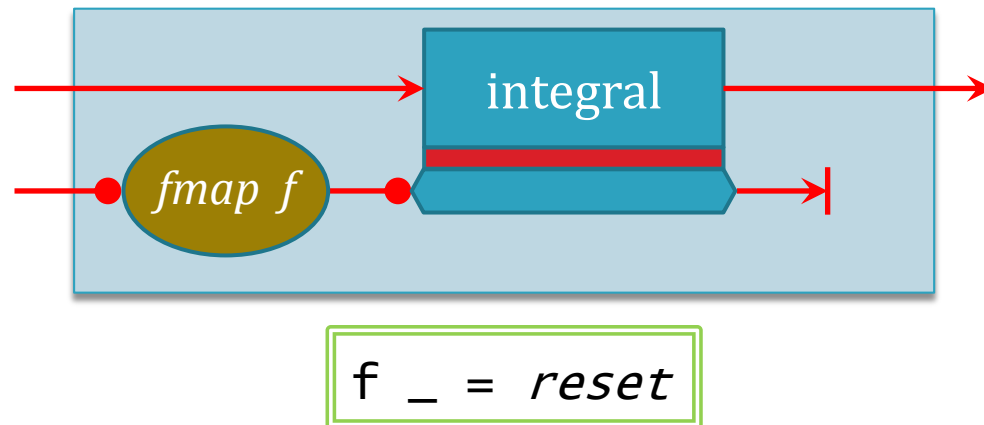
- The top wires are the standard signals.
- The bottom wires are **State** signals.
 - The input Event State can be used to change sf 's internal state.
 - The output State is used to capture the current internal state.

Settable Laws



Example: IntegralReset

- Settability makes our original problem trivial:



- We no longer need the overkill of lifting a signal function to the signal level.



Optimization

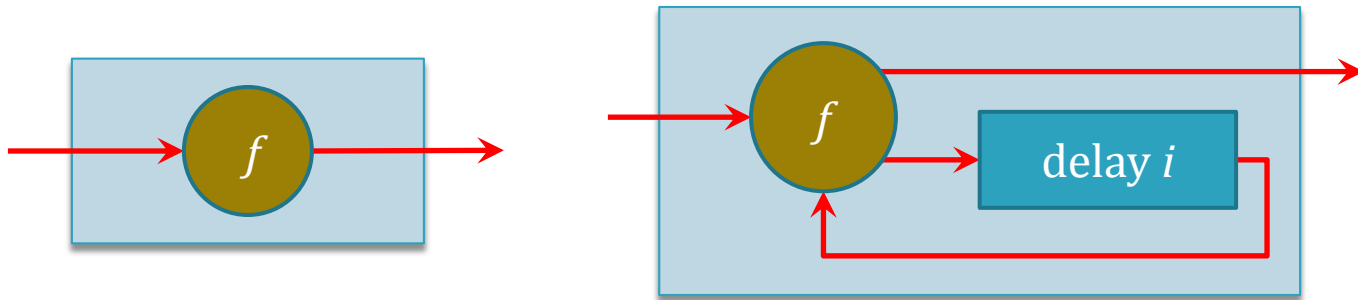
The benefit of static arrows over dynamic arrows

Causal Commutative Arrows

- Liu, Cheng, Hudak [JFP '11] introduced CCA
 - ▣ CCAs can be heavily optimized.
 - ▣ Performance increases 10-40 times.
 - ▣ CCAs do not allow switch but do allow choice.
- CCAs can allow Non-Interfering choice.
 - ▣ Arrowized recursion is not supported by default, but it can be added.

How CCA Works

- The CCA optimization reduces arrows to one of two forms:



- We extend this with the ability to handle arrowized recursion and call it CCA*.

Performance Results

| | GHC | CCA* + Stream |
|-------------------------|------------|----------------------|
| Chained Adder | 1.0 | 4.06 |
| Chained Integral | 1.0 | 13.27 |
| Dynamic Counters | 1.0 | 10.91 |

- 3 sample programs using arrowized recursion.
- The 10x performance increase is comparable to Liu et al's results.
 - ▣ The Chained Adder is stateless, and thus more optimized by GHC.